

The SXS Catalog of Simulations

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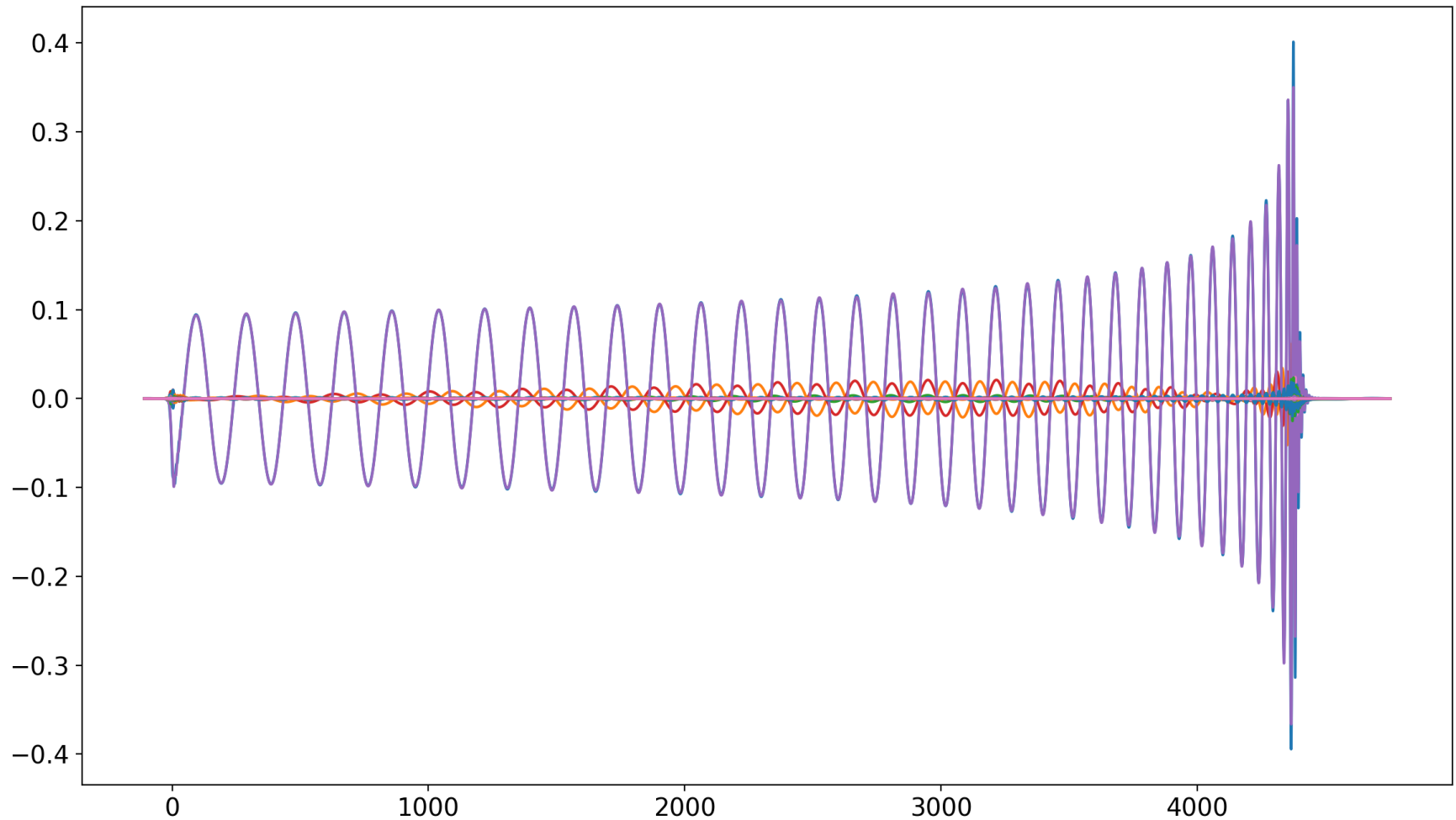
Outline

- Simulations
 - SpEC
 - The numbers
 - Post-processing
- The data
 - What's included
 - How to get it
 - Formats
 - Problems
 - Solutions
- Software
 - Backwards compatible
 - Future proof

```
In [1]: import numpy as np
import matplotlib.pyplot as plt
import sxs

waveform = sxs.load("SXS:BBH:0123/Lev/rhOverM", extrapolation_order=2, download=True)
plt.plot(waveform.t, waveform.data.real);
```

Skipping download from 'https://data.black-holes.org/catalog.json' because local file is newer
Found the following files to load from the SXS catalog:
SXS:BBH:0123v4/Lev5/rhOverM_Asymptotic_GeometricUnits_CoM.h5



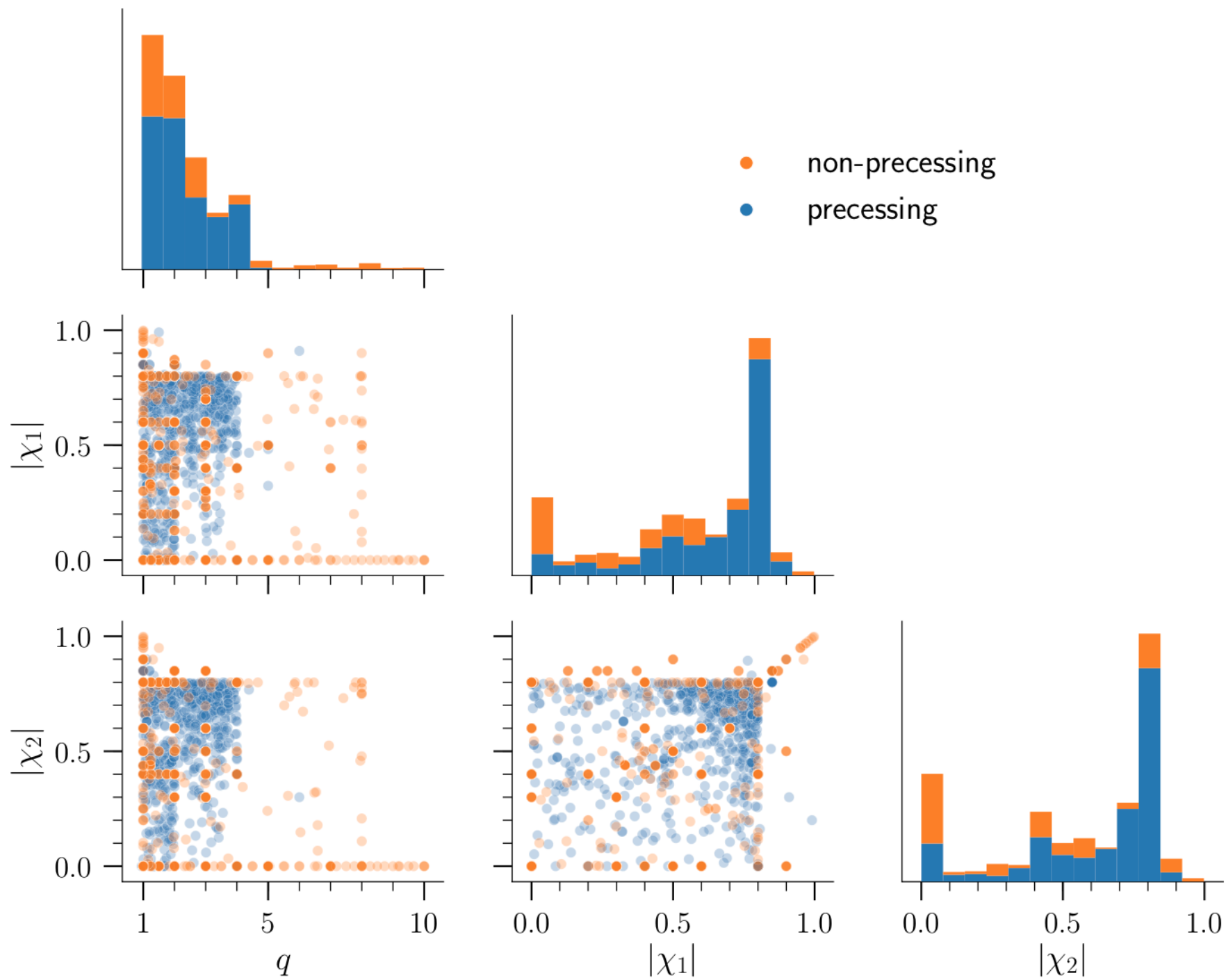
SpEC

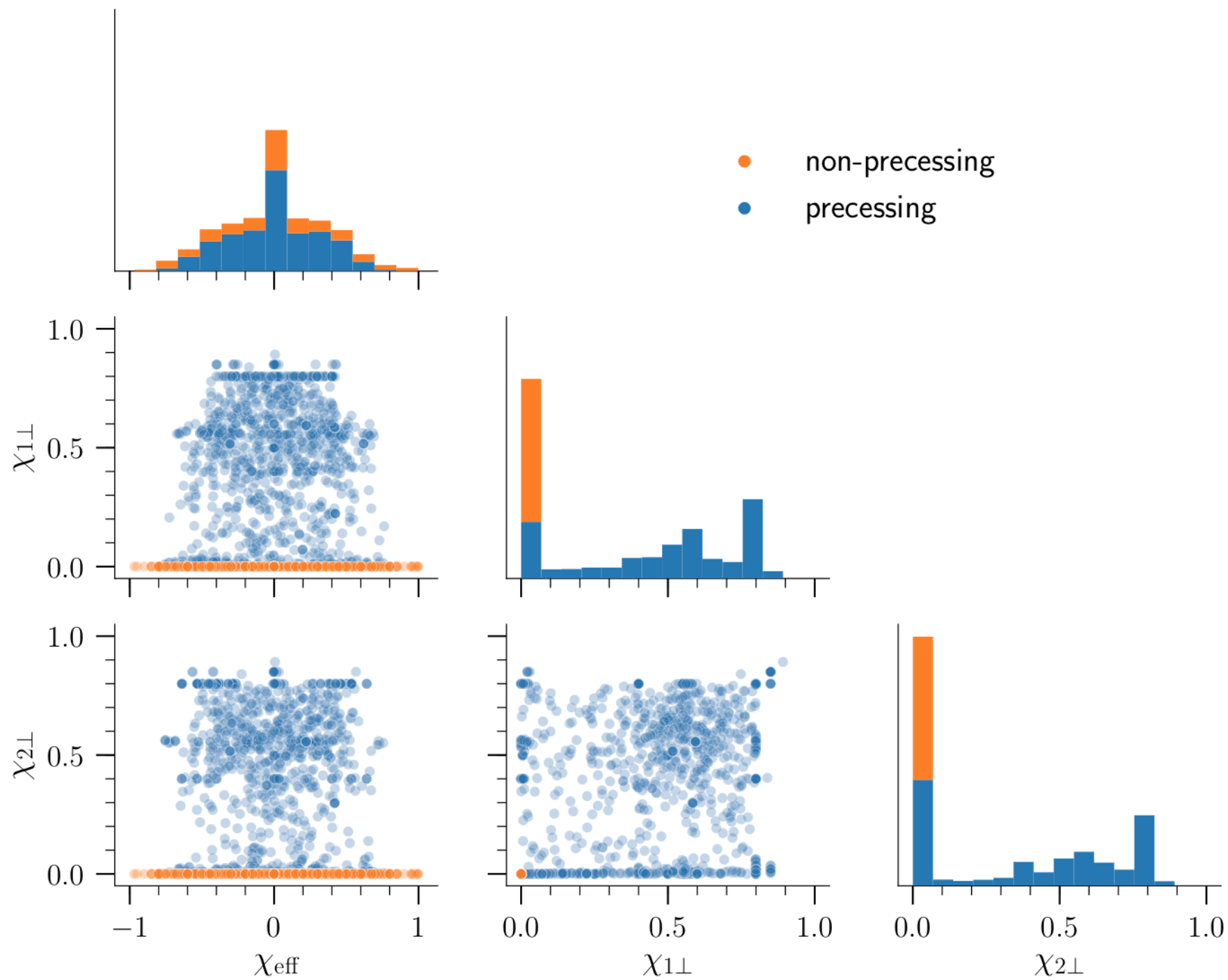
- Initial data solves extended conformal thin sandwich equations
- Iterate to reduce eccentricity if desired
- Multi-domain spectral methods
- First-order generalized harmonic with constraint damping
- Adaptive mesh refinement
- Constraint-preserving boundary conditions

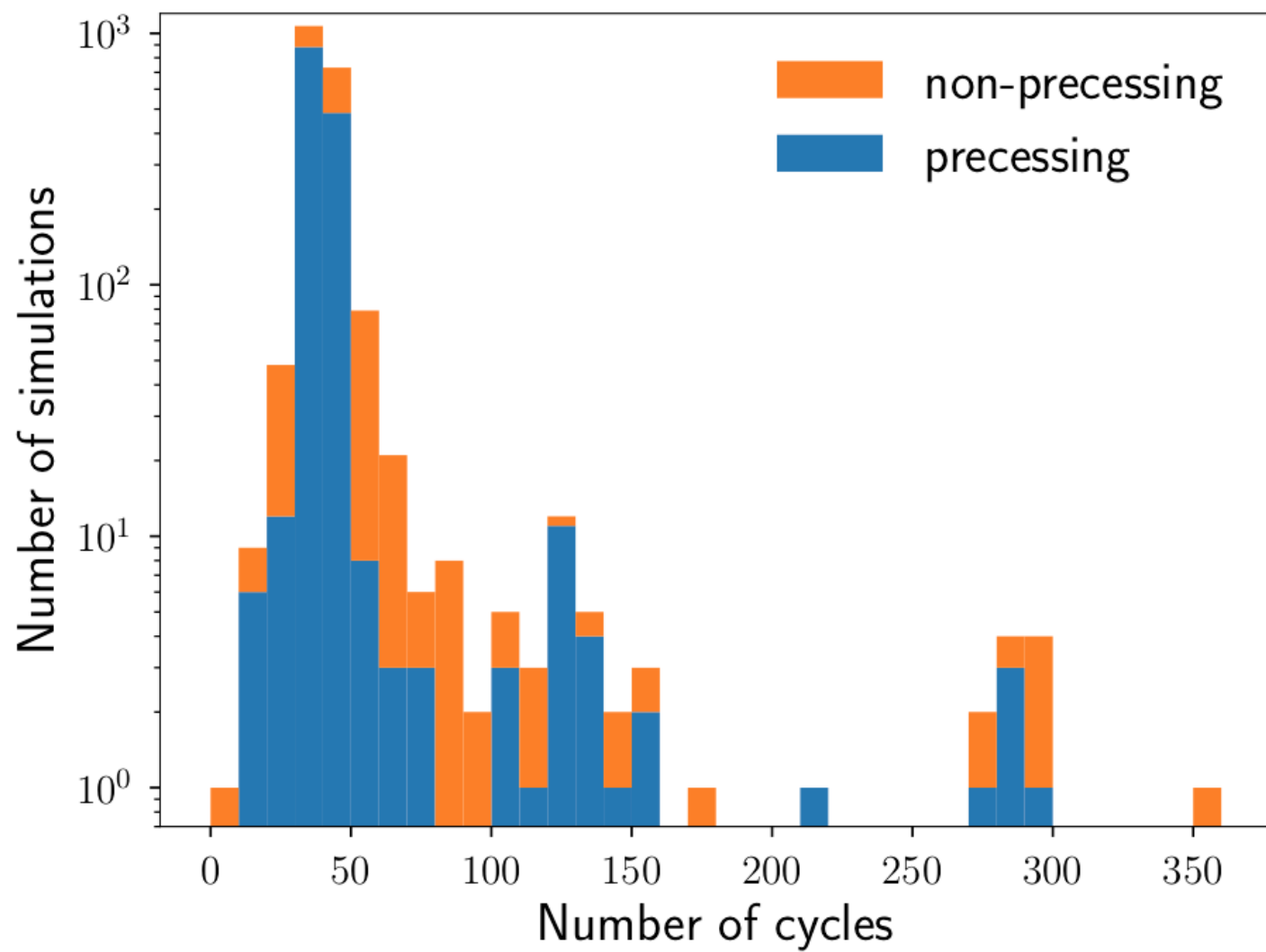
<https://arxiv.org/abs/1904.04831> (<https://arxiv.org/abs/1904.04831>)

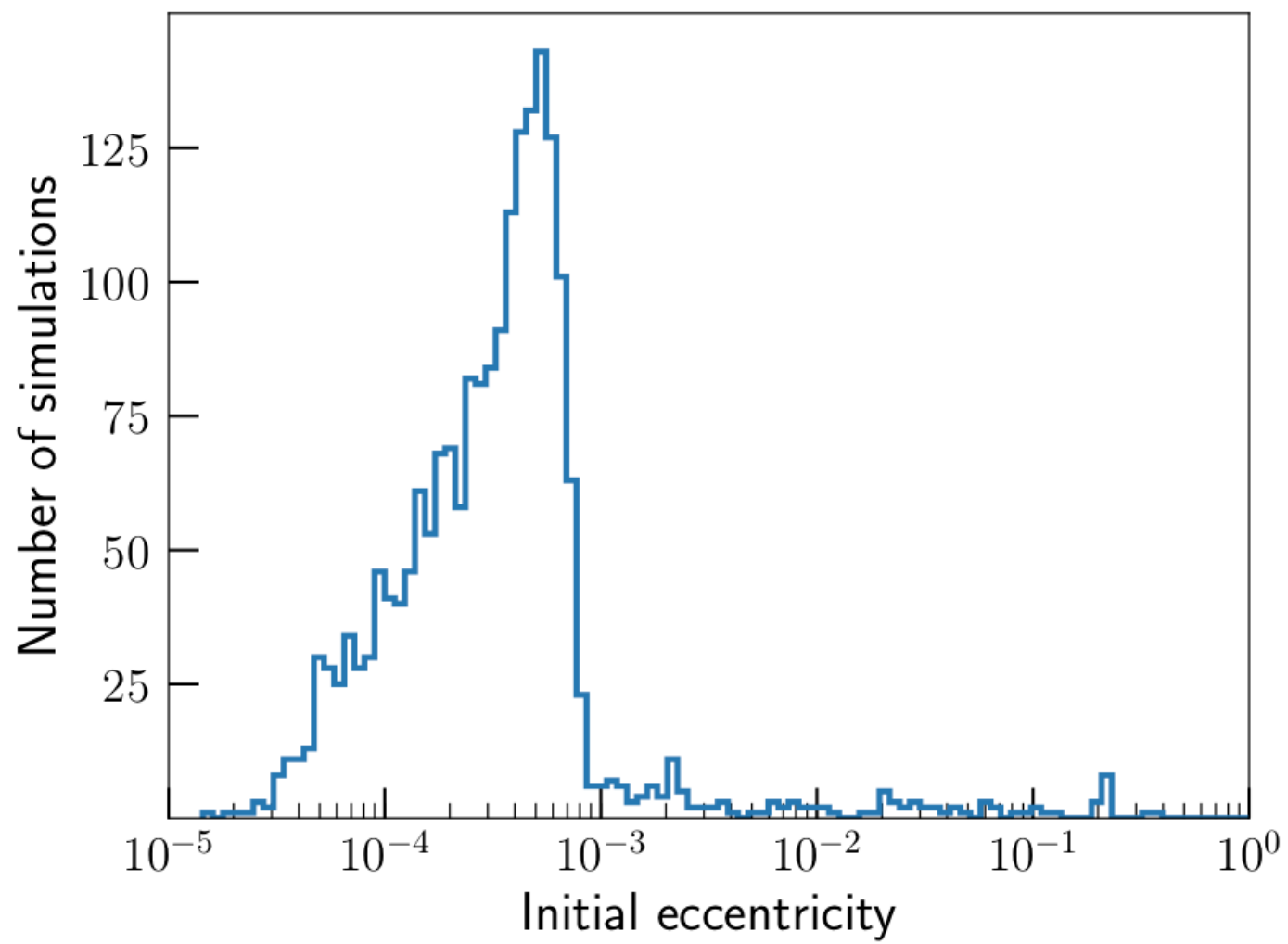
Simulations

- 2 NSNS
- 7 BHNS
- 2019 BBH
 - mass ratios between 1 and 10
 - spin magnitudes up to 0.998
 - 1426 precessing simulations
 - typically ~ 19 orbits









Data extracted during the runs

- Horizon information
 - Coordinate trajectories
 - Areal (irreducible) mass
 - Christodoulou mass
 - Spins
- On a series of ~ 24 spheres between $\sim 100M$ and outer boundary
 - RWZ h modes
 - Ψ_4 modes
 - Surface area
 - Average lapse
- (Data for CCE)

Post-processing

- (CCE, soon)
- Extrapolation of Ψ_4 and h
- Center-of-mass correction

Extrapolation

- Define corrected retarded time on each sphere

$$u_{i,j} = \int_0^{T_i} \sqrt{\frac{-1/g_j^{TT}(T)}{1 - 2M_{\text{ADM}}/R_j(T)}} dT - R_j(T_i) - 2M_{\text{ADM}} \ln \left[\frac{R_j(T_i)}{2M_{\text{ADM}}} - 1 \right],$$

- Fit the waveforms with a simple

$$f(u, r) \approx \sum_{j=0}^N \frac{f_{(j)}(u)}{r^j}$$

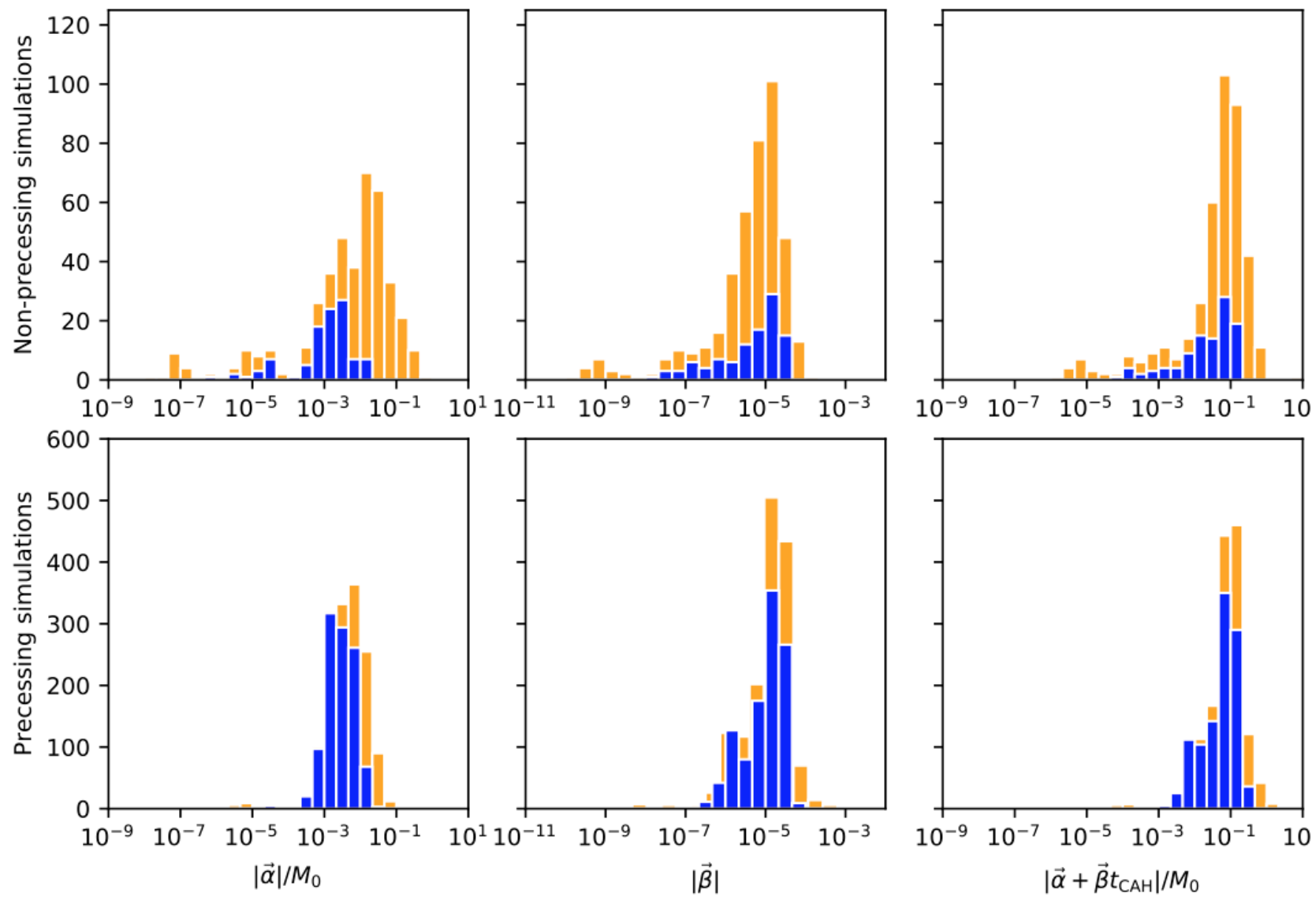
- Extrapolated waveform is $f_{(0)}(u)$

CoM correction

- "Gauge-invariant waveforms" 🙄
- Displacements around 0.1M show up as big wiggles
- General BMS transformations allowed
- We just use boost and translation
- Even worse, we just use the horizon trajectories

<https://arxiv.org/abs/1509.00862> (<https://arxiv.org/abs/1509.00862>)

<https://arxiv.org/abs/1904.04842> (<https://arxiv.org/abs/1904.04842>)



The problem

- Total catalog is ~16 TB
- Extrapolated waveform files currently average 95 MB each
- Users who want one waveform from each simulation need ~200 GB
- This is accelerating

The solutions

- Eliminate redundant time data — factor of ~1.45 reduction
 - Reduce the number of files — factor of ~8 reduction
 - Eliminate finite-radius files
 - Eliminate non-CoM files
 - Store each file more efficiently — factor of ~4 reduction
-
- Total catalog size falls to ~500 GB
 - Typical user needs ~10 GB

Proposed spec

Requirements

- H5 file
 - All datasets stored as XOR-ed UINT64s
 - Attribute format
 - Dataset time
 - Shape (n_times,)
 - Must be strictly monotonic
 - Dataset modes
 - Shape (n_times, 2*n_modes)
 - Conjugate-pair representation
 - Attribute ell_min
 - Attribute ell_max
 - Dataset log_frame (optional)
 - Shape (0, 3), (1, 3), or (n_times, 3)
- JSON file
 - same file name with .h5 → .json
 - more details on later slides

Recommendations

- Corotating frame
- Truncation at 10^{-10} of norm
- Add 0.0
- Compression options
- Choices of which files to distribute
- Directory structure and file names

Corotating frame

- Defined as rotating frame that minimizes time dependence of modes
- Compute angular velocity of this frame by solving

$$\langle h | L \cdot \vec{\omega} | h \rangle = -\langle h | L \partial_t | h \rangle$$

- The integrate the angular velocity to find a frame
- Constant of integration \rightarrow align z with dominant eigenvector of $\langle h | L L | h \rangle$

<https://arxiv.org/abs/1302.2919> (<https://arxiv.org/abs/1302.2919>)

Conjugate-pair mode representation

- $h_{\ell,m}$ and $h_{\ell,-m}$ are at least somewhat redundant in corotating frame
- Define

$$s_{\ell,m} = \frac{h_{\ell,m} + \bar{h}_{\ell,-m}}{\sqrt{2}}$$

$$d_{\ell,m} = \frac{h_{\ell,m} - \bar{h}_{\ell,-m}}{\sqrt{2}}$$

- One of these will be zero (non-precessing systems) or small (otherwise), and thus compress well
- Store

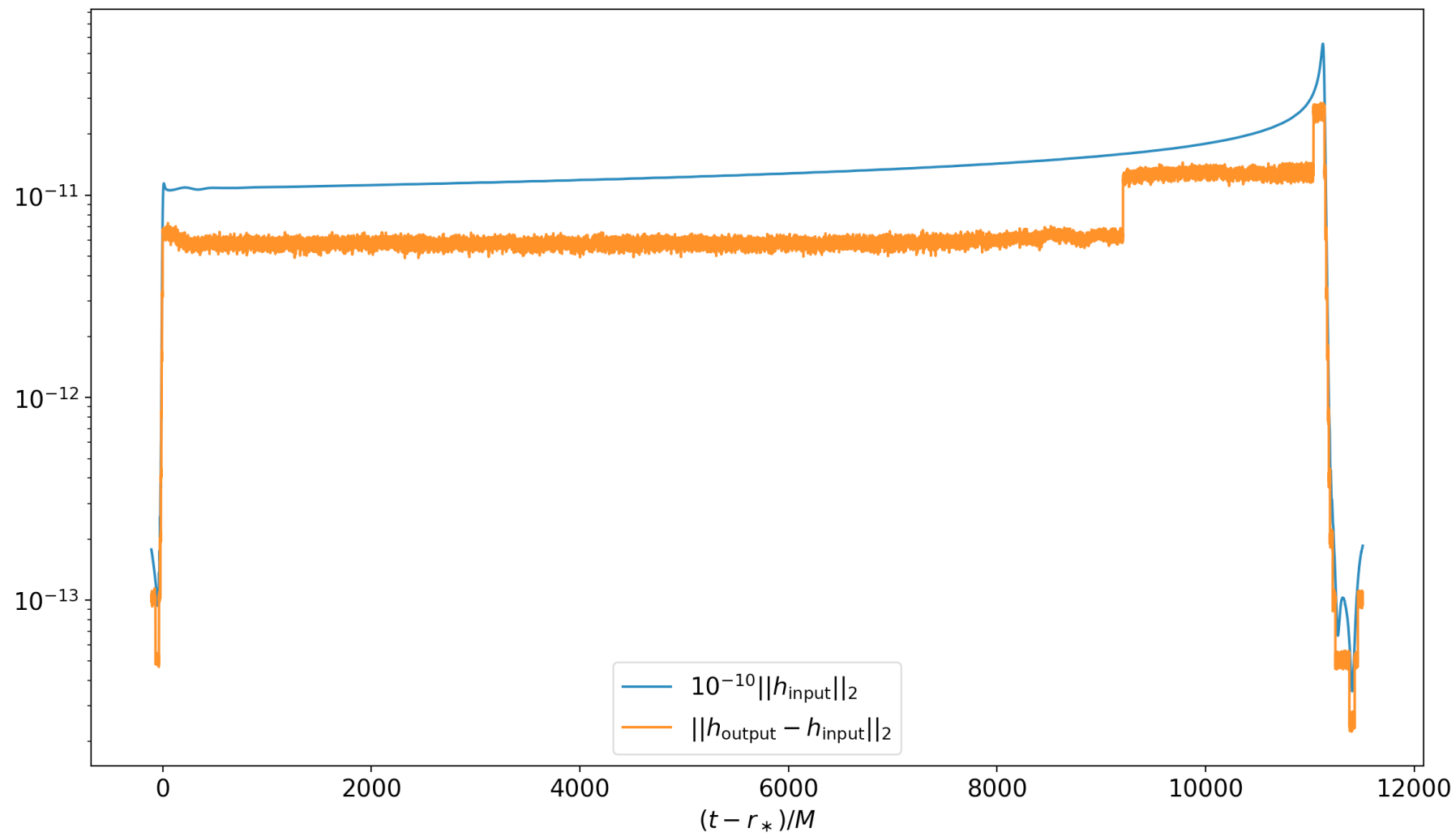
$[d_{2,2}, d_{2,1}, h_{2,0}, s_{2,1}, s_{2,2}, d_{3,3}, d_{3,2}, d_{3,1}, h_{3,0}, s_{3,1}, s_{3,2}, s_{3,3}, \dots]$

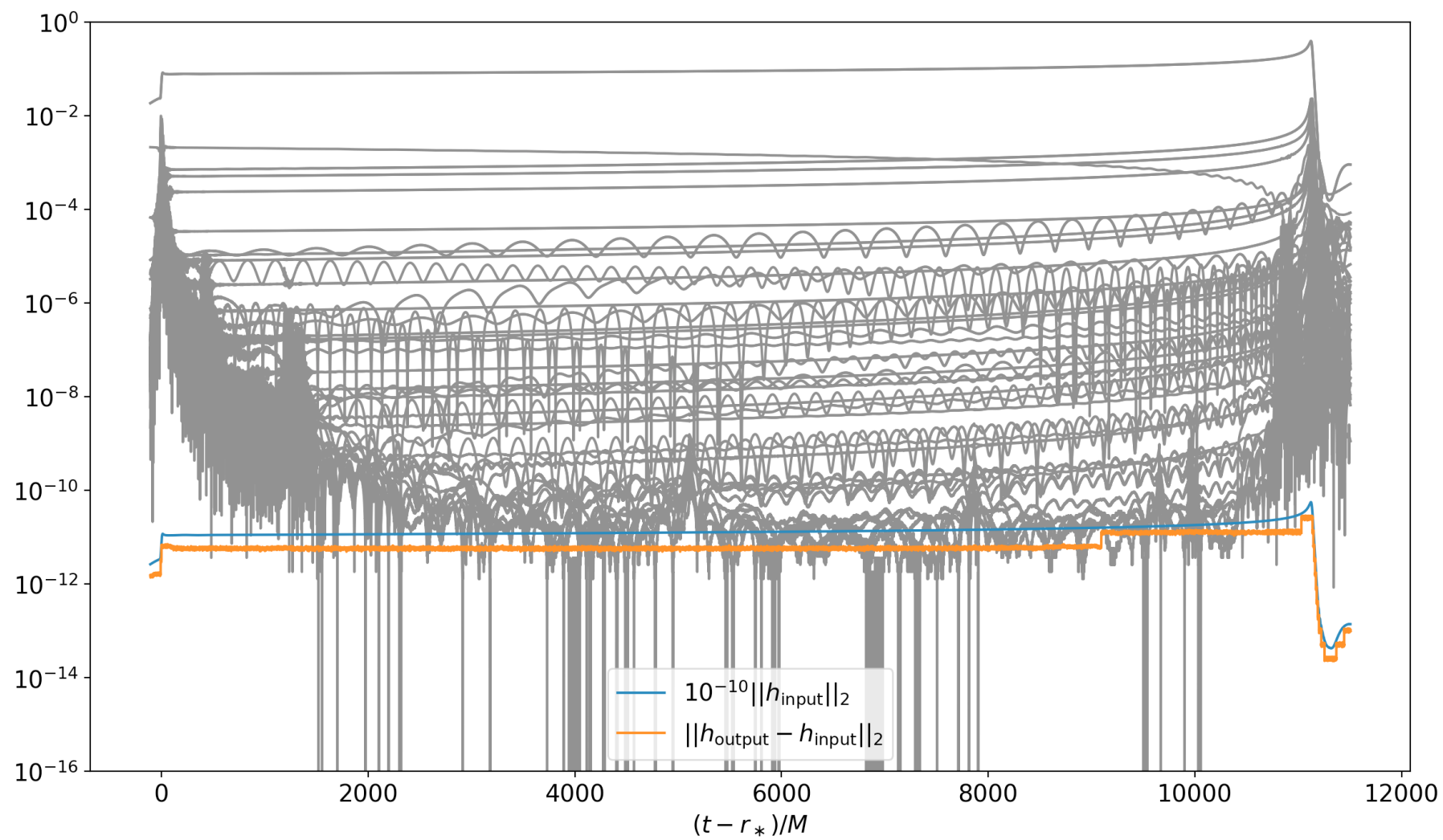
Truncation

Zero out bits that affect norm at level below some chosen tolerance

- Only non-exact step
- Choose the *relative* tolerance `tol`
- Defines the *absolute* tolerance `tol * norm(data)` as function of time
- Drop bits at lower significance from conjugate-pair modes

```
def truncate(data, n_modes, tol=1e-10):  
    tol /= sqrt(n_modes) # Distribute ~evenly among all modes  
    abs_tol = tol * norm(data, axis=1)  
    power_of_2 = 2 ** (floor(-log2(abs_tol))) # 1 / (largest power of 2 <= abs_tol)  
    return round(data * power_of_2) / power_of_2
```





Add 0.0

- Before truncation, many modes were small and noisy
- Signs were basically random
- After truncation, they are now ± 0.0
- The sign doesn't matter, but flips randomly, thus not compressing well
- Get rid of it by adding 0.0

XOR with previous time step

- Bitwise difference between data at successive times
- For ~smooth data, we are left with few bits changing
- This compresses *very* well
- It's trivial to do, and to undo:

Shuffle

- Bytes of similar significance more correlated than consecutive bytes
- Store bytes of given significance consecutively

```
In [5]: for n in np.random.rand(8): print(f"{n.view(np.uint64):064b}\n")
```

0011111111010111011110101111000001100101001000010001000011110010

001111111101100001110010010001110111111110100111010110100000100

0011111111010000001001011010100110110110010011010100010100011000

0011111101010000011011000011000101001101110010111011110000000000

0011111111010110101000011110111001110101100110100001110001011000

001111111110110011010111110000111111001110111011000111111111100

0011111111100100111001111100110110101000110011111111010001011

0011111111100000111001001101010101010010110101000000001011100101

Format

- Corotating frame
- Paired modes
- Truncate
- XOR
- Multishuffle
- Bzip2

Are you scared yet?

Changing to a new format

- Pros:
 - Significant reduction in size
 - ~No cost to add insignificant modes
 - Easier for maintainers
 - Easier for users
- Cons:
 - Different is bad

Solve the problem with code

- `GWFrames` — old and ugly
- `scli` - powerful but complicated
- `sxs` - new and beautiful